

Föreläsningsspass 4:

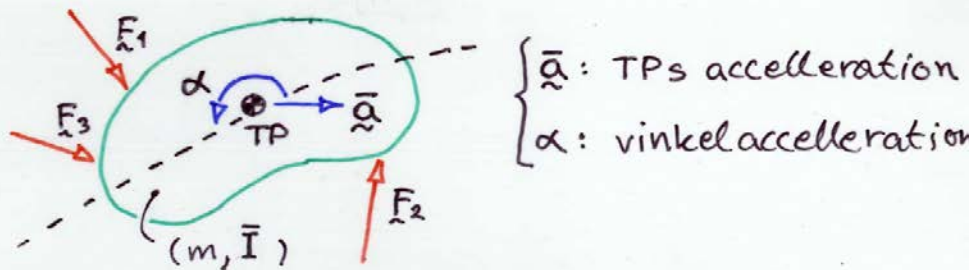
- * Intro. till dynamiken
- * Partikelkinematik 1D

Avsnitt i kursboken: 5.1

DYNAMIK - JÄMVIKT-STATIK

* DYNAMIK:

Stel kropp påverkad av krafter och moment (massa m , tröghetsmoment \bar{I})

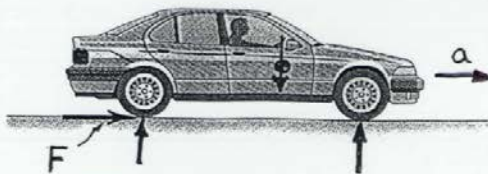


Rörelse-
ekvationerna:

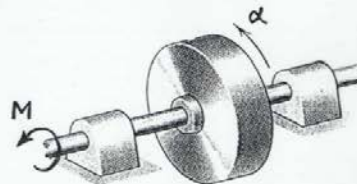
$$\left\{ \begin{array}{l} \sum F_i = m \cdot \bar{a} \\ \overset{\curvearrowright}{\text{TP}} \sum M_i = \bar{I} \cdot \alpha \end{array} \right.$$

obalanserade krafter \Rightarrow acceleration \bar{a}
 — u — moment \Rightarrow vinkelacc. α

Massa m ger motstånd mot acc. \bar{a}

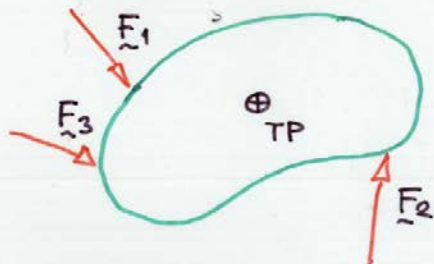


Tröghetsmom. \bar{I} ger motstånd mot vinkelacc. α



DYNAMIK - JÄMVIKT - STATIK forts.

* JÄMVIKT:



Krafter och moment
i balans dvs -

$$\begin{cases} \sum \vec{F}_i = 0 \\ \sum M_i = 0 \end{cases}$$

Rörelse ekv. $\Rightarrow \bar{\vec{a}} = 0$ och $\alpha = 0$

Alltså $\begin{cases} \text{TPs hastighet } \bar{\vec{v}} = \text{konst.} \\ \text{Vinkel hastighet } \omega = \text{konst.} \end{cases}$

* STATIK:

Behandlar kroppar i vila som uppfyller: $\begin{cases} \bar{\vec{v}} = 0 \\ \omega = 0 \end{cases}$

Jämvikts-
ekvationerna: $\begin{cases} \sum \vec{F}_i = 0 \\ \sum M_i = 0 \end{cases}$

Anm. Momentpunkten är inte begränsad till TP i statiken.

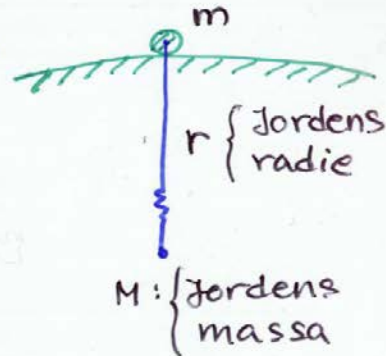
TYNGDKRAFT JÄMFÖRT MED "TRÖGHETSKRAFT"

Newton formulerade ett konsekvent kraftbegrepp:

a) Gravitationskraften vid jordytan

Gravitationslagen \Rightarrow

$$F = G \frac{Mm}{r^2} = \underline{mg}$$

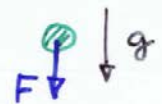


b) Fallande massa vid jordytan

Massan får accelerationen $g = 9.81 \text{ m/s}^2$

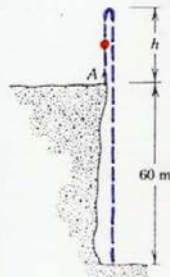
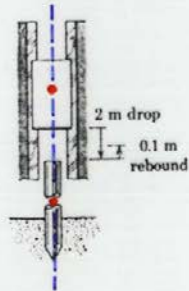
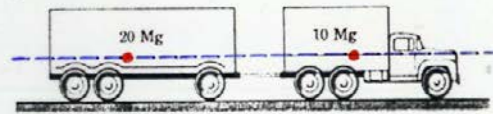
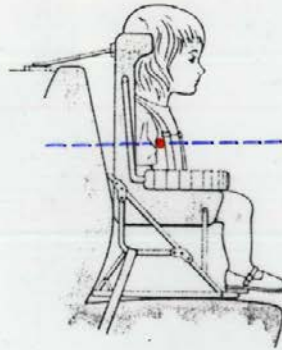
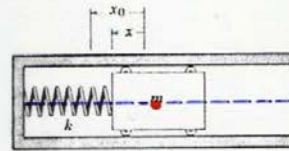
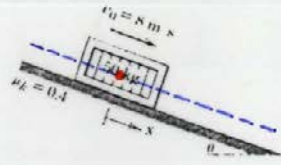
Newtons 2:a lag $F = ma$:

$$a = g \Rightarrow F = \underline{mg}$$



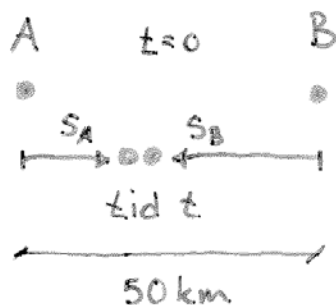
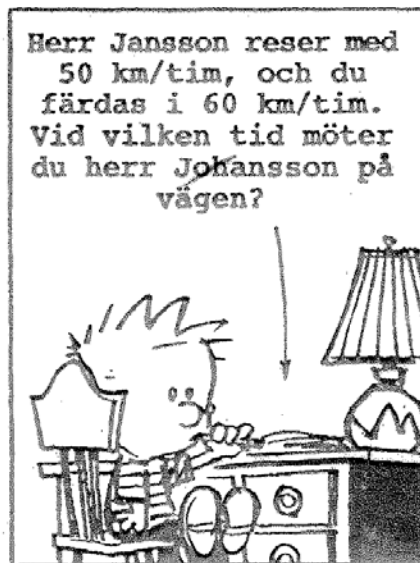
a) och b) ger samma kraft!

RÄTLINJIG RÖRELSE



KALLE & HOBBE

av Bill Watterson



$$S_A + S_B = 50 \text{ km}$$

$$\frac{S_A}{t} = 50 \text{ km/h}$$

$$\frac{S_B}{t} = 60 \text{ km/h}$$

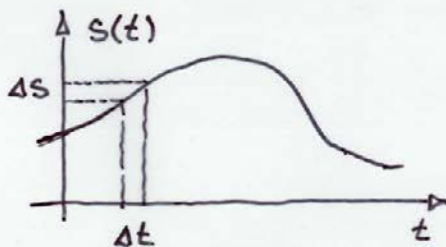
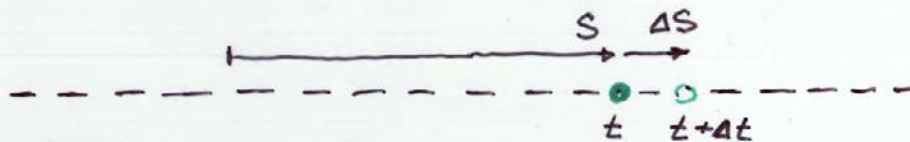
$$50t + 60t = 50 ; t = \frac{50}{110} = 0.45 \text{ h}$$

Svar : 17:27



DEFINITION AV HASTIGHET OCH ACCELERATION

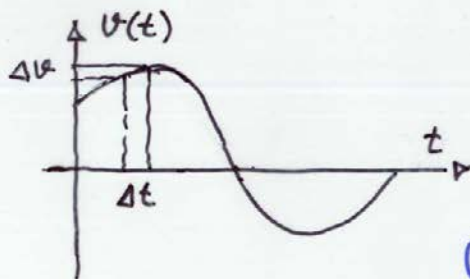
Partikel i rätlinjig rörelse:



Medelhastighet: $\frac{\Delta s}{\Delta t}$

$$v = \lim_{\Delta t \rightarrow 0} \frac{\Delta s}{\Delta t} = \frac{ds}{dt} \quad \dots (1)$$

Momentan hastighet



Medelacceleration: $\frac{\Delta v}{\Delta t}$

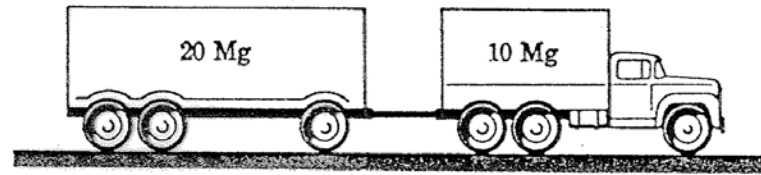
$$a = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt} \quad \dots (2)$$

Momentan acceleration

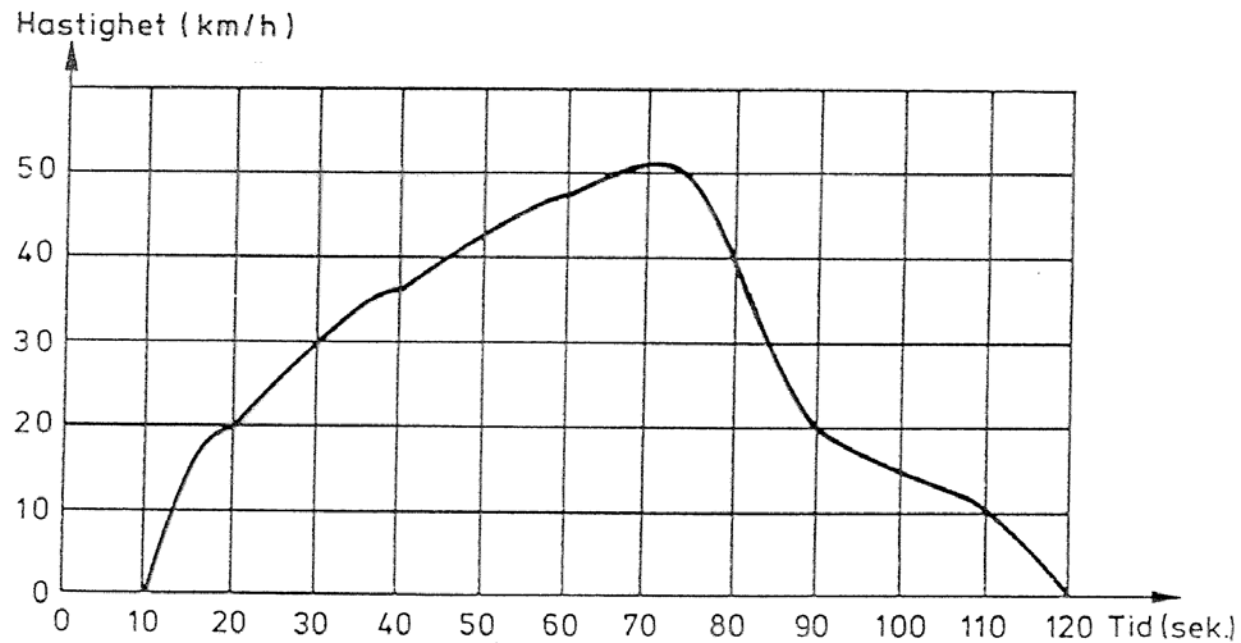
Desutom (1) i (2) $\Rightarrow a = \frac{d^2s}{dt^2}$

Anm. Fart: Belopp av hastighet $|v|$

Ex. Färdskrivare



Problem 3/2



Ex. Usain Bolt; 100m-lopp

Topp hastighet?

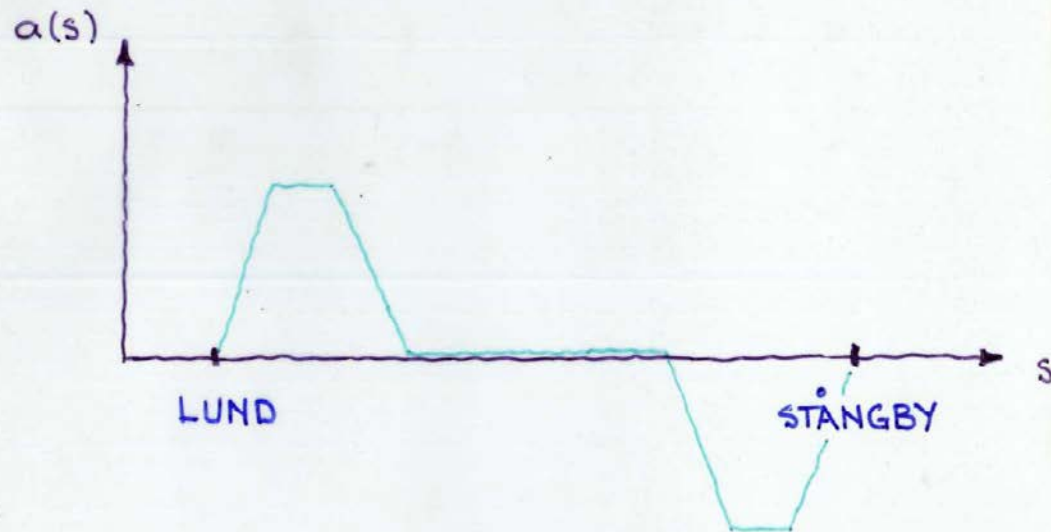
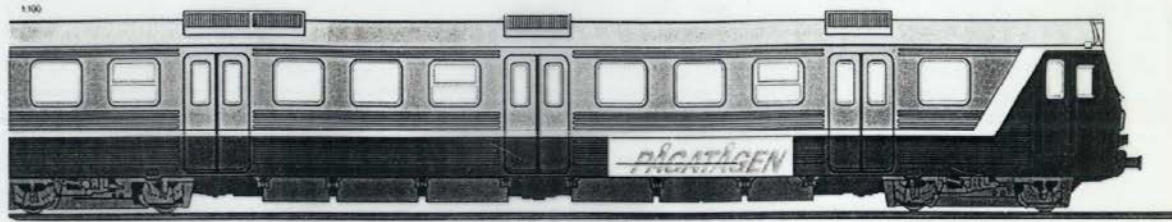


Usain Bolt



WR 9:58

ACCELERATION SOM FUNKTION AV STRÄCKA



ALTERNATIVT UTTRYCK FÖR ACCELERATION

Användning av kedjeregeln i definitionen av acceleration:

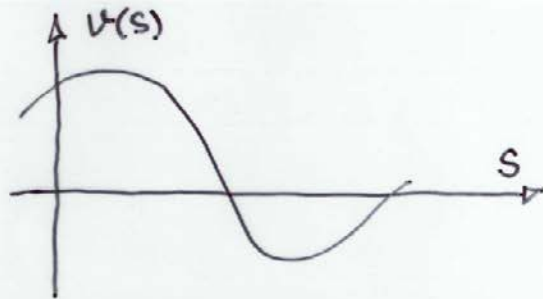
$$a = \frac{dv}{dt} = \frac{dv}{ds} \frac{ds}{dt} = \frac{dv}{ds} v$$

dvs tidsvariabeln har eliminerats

Alltså

$$a = v \frac{dv}{ds}$$

Hastigheten betraktas nu som en funktion av läget:



Anm. a kan vara en funktion av s eller v.