



## MODELLING NON-LINEAR DYNAMICS OF RUBBER BUSHINGS - Parameter Identification and Validation

Anders Persson and Fredrik Karlsson

### Presentation

Spring of 2003

### Report

will be published as report TVSM-5119

### Supervisors

Per-Erik Austrell, *Ph.D.*  
*Div. of Structural Mechanics*

Jan Hellberg, *M.Sc.*  
*Vehicle Dynamics, Volvo Car Corp.*

Anders Wirje, *M.Sc.*  
*Strength and Durability Center, Volvo Car Corp.*

### The work is performed at

Div. of Structural Mechanics,  
Lund Institute of Technology,  
Lund University

### In cooperation with

Volvo Car Corporation  
and Forsheda



LUND  
UNIVERSITY

### Background

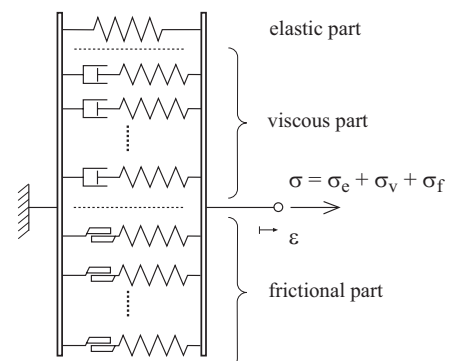
Rubber bushings can be found in all vehicle suspension systems. The suspension components are connected to each other, to the subframe, and to the body structure via rubber bushings. They are a key element in designing desired quasi-static and dynamic behaviour of suspension systems. The dynamic characteristics of a rubber bushing are often very complex in nature, due to the fact that the response is dependent on several variables, such as displacement, frequency, amplitude, preload, and temperature. The displacement dependence is predominant, but the other dependencies can be absolutely critical in capturing the mechanical behaviour.

### Assignment

The ultimate objective is to establish a methodology for rubber bushing modelling and parameter identification.

### Major activities

- Create and study different 1-D bushing models in MATLAB:
  - Visco-elastic models including the Kelvin-Voigt model (no amplitude dependence).
  - Elasto-plastic models (no frequency dependence).
  - Generalized visco-plastic (viscoelastic-elastoplastic) models (both frequency and amplitude dependence).



Generalized visco-plastic material model

- Develop a methodology for model parameter identification from physical component tests.
- Validate the bushing models by comparison with component testing.

### Validation

Three rubber components will be used to validate the bushing models for quasi-static and harmonic dynamic behaviour. Two of the components are geometrically simple model components and the third is an actual component used in a Volvo car.